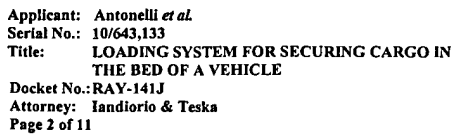


A 3D coordinate system is shown with three axes originating from a central point. The vertical axis is labeled 'V' at its top. The axis extending towards the upper right is labeled 'H' at its tip. The axis extending towards the upper left is labeled 'T' at its tip. The axes are represented by lines with arrows at their ends.

FIG. 1 is a perspective view of a mobile device 10 mounted on a vehicle 12. The device 10 includes a display 22, a camera 20, and a sensor 24. The vehicle 12 includes a rear wheel 14 and a front wheel 16. The device 10 is connected to the vehicle 12 via a cable 18.

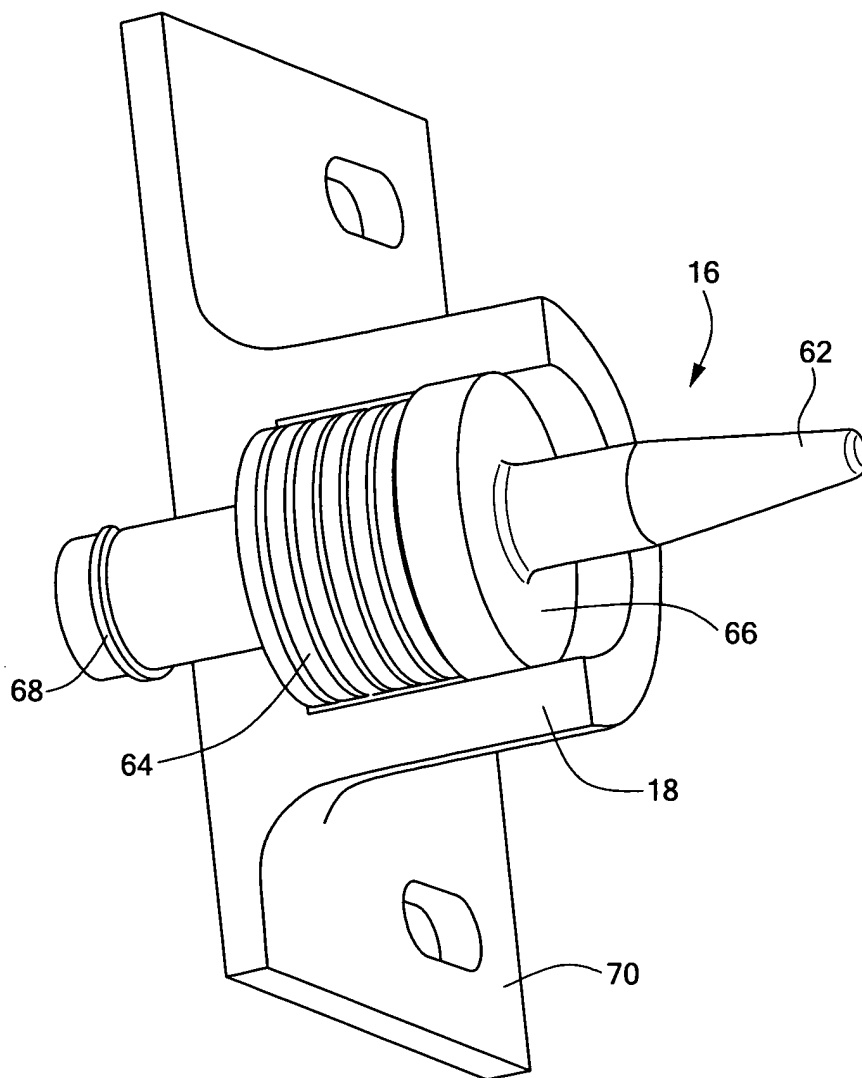




**FIG. 3**



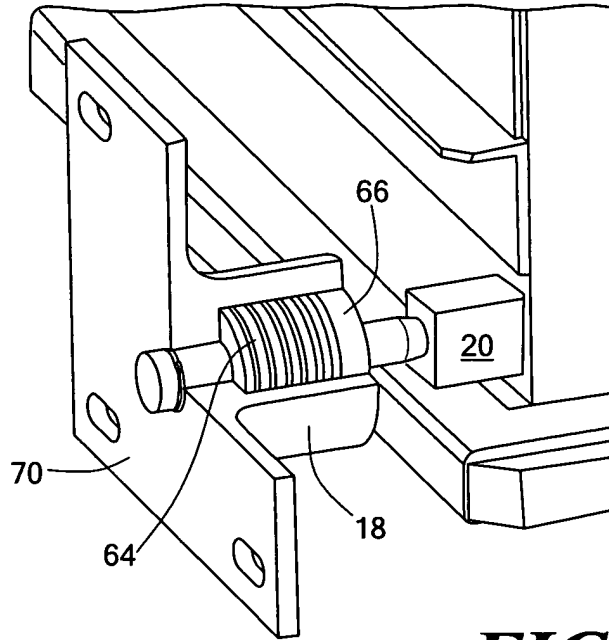
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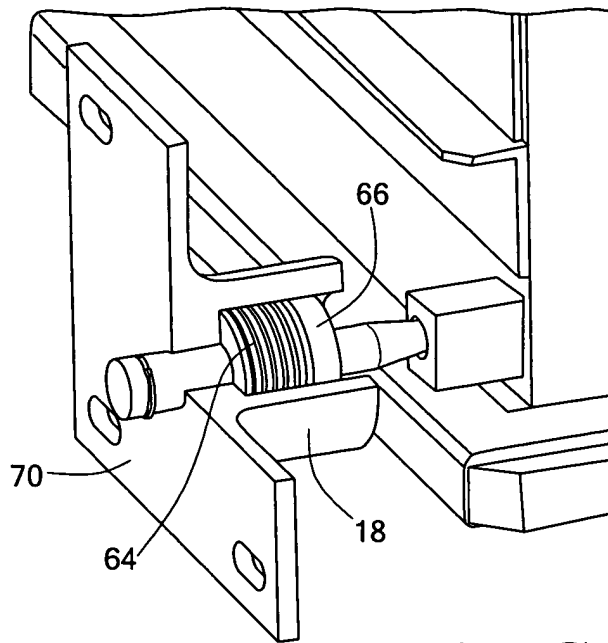
**FIG. 4**



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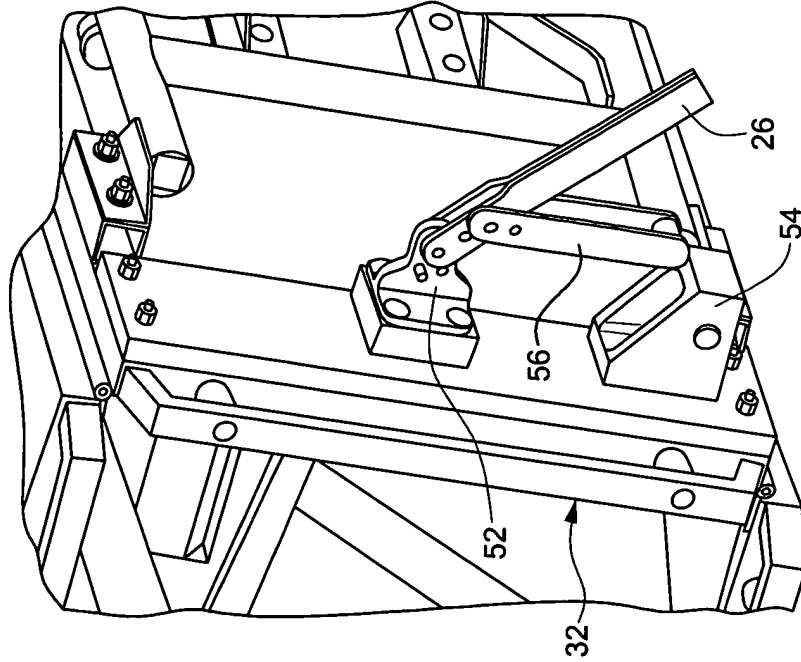
**FIG. 5**



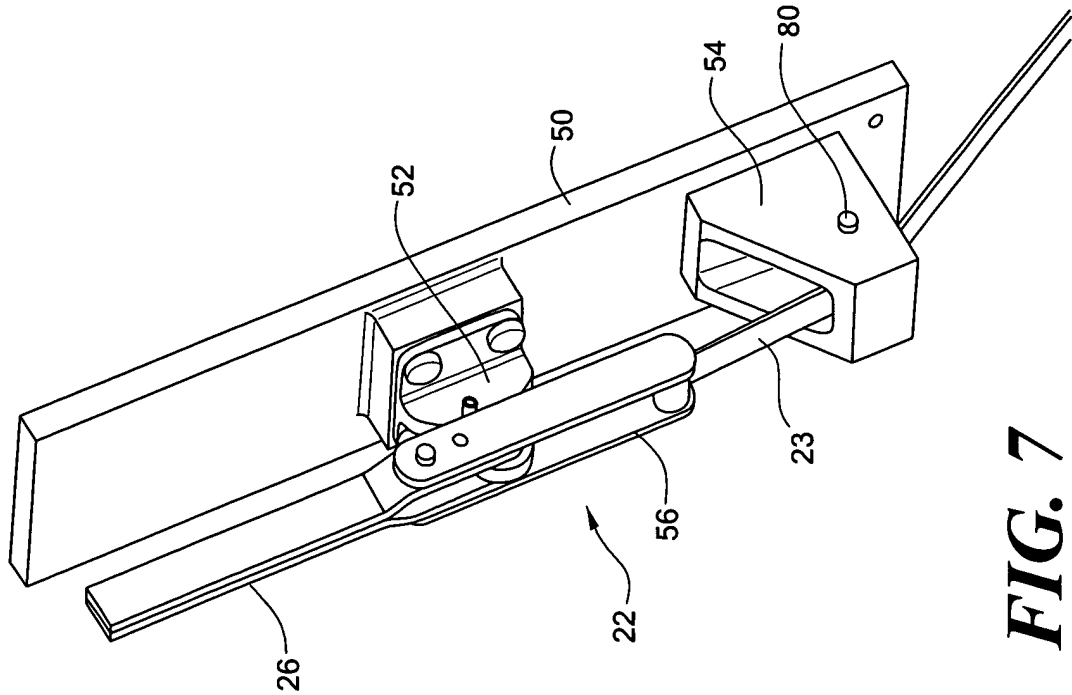
**FIG 6**



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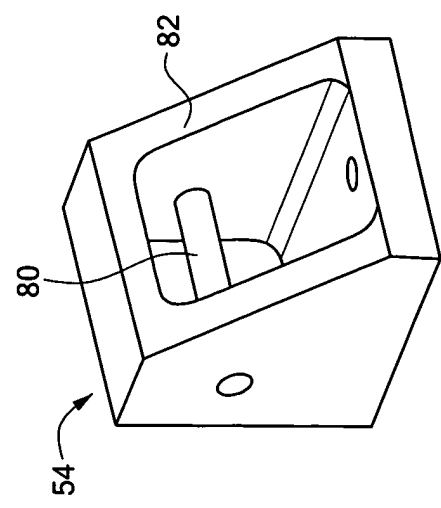
**FIG. 8**



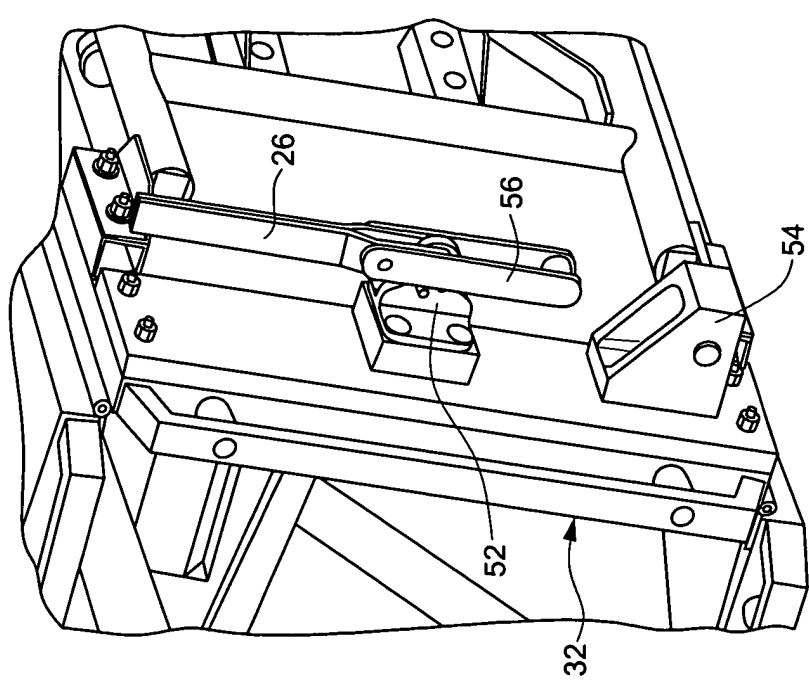
**FIG. 7**



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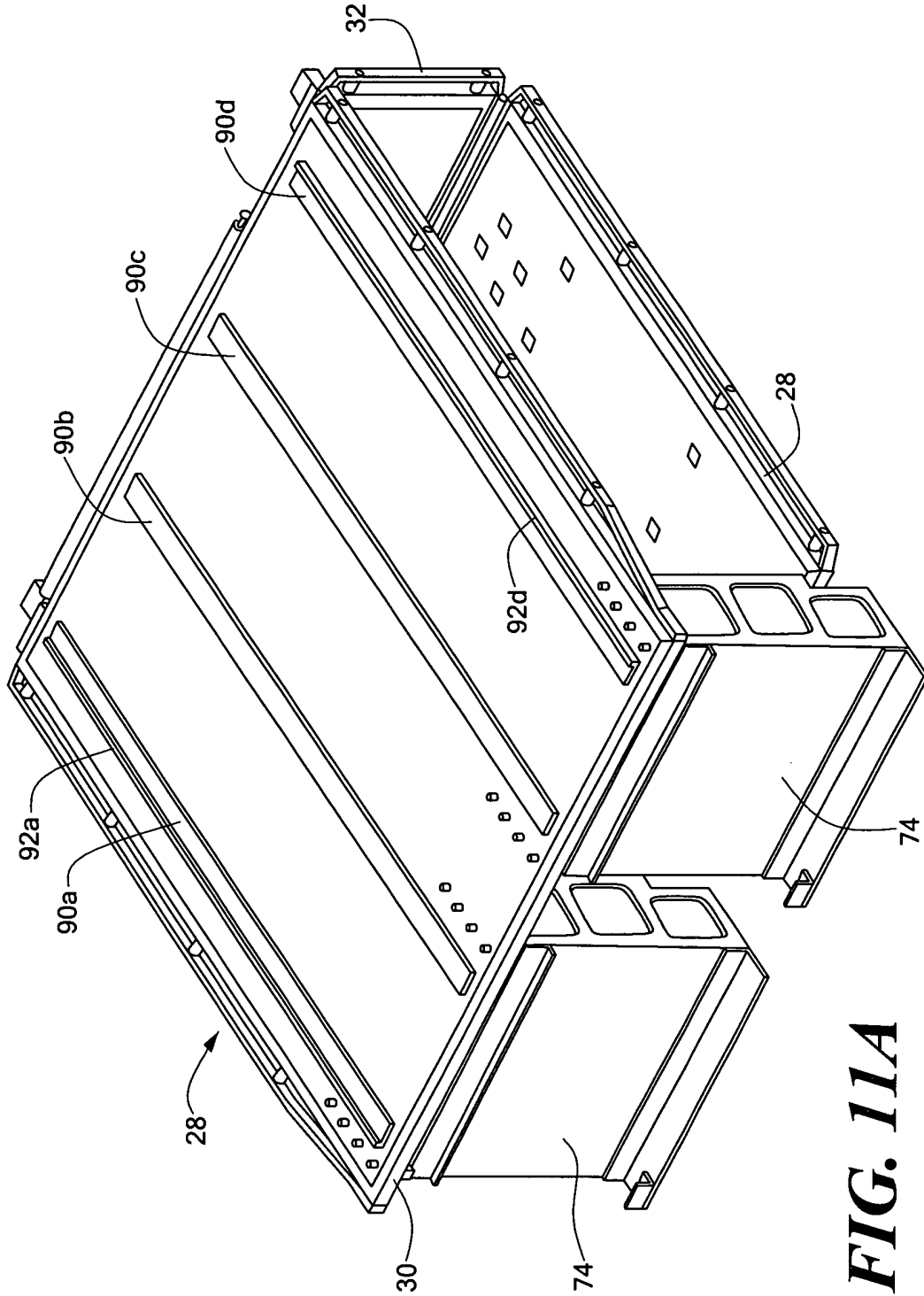
**FIG. 10**



**FIG. 9**



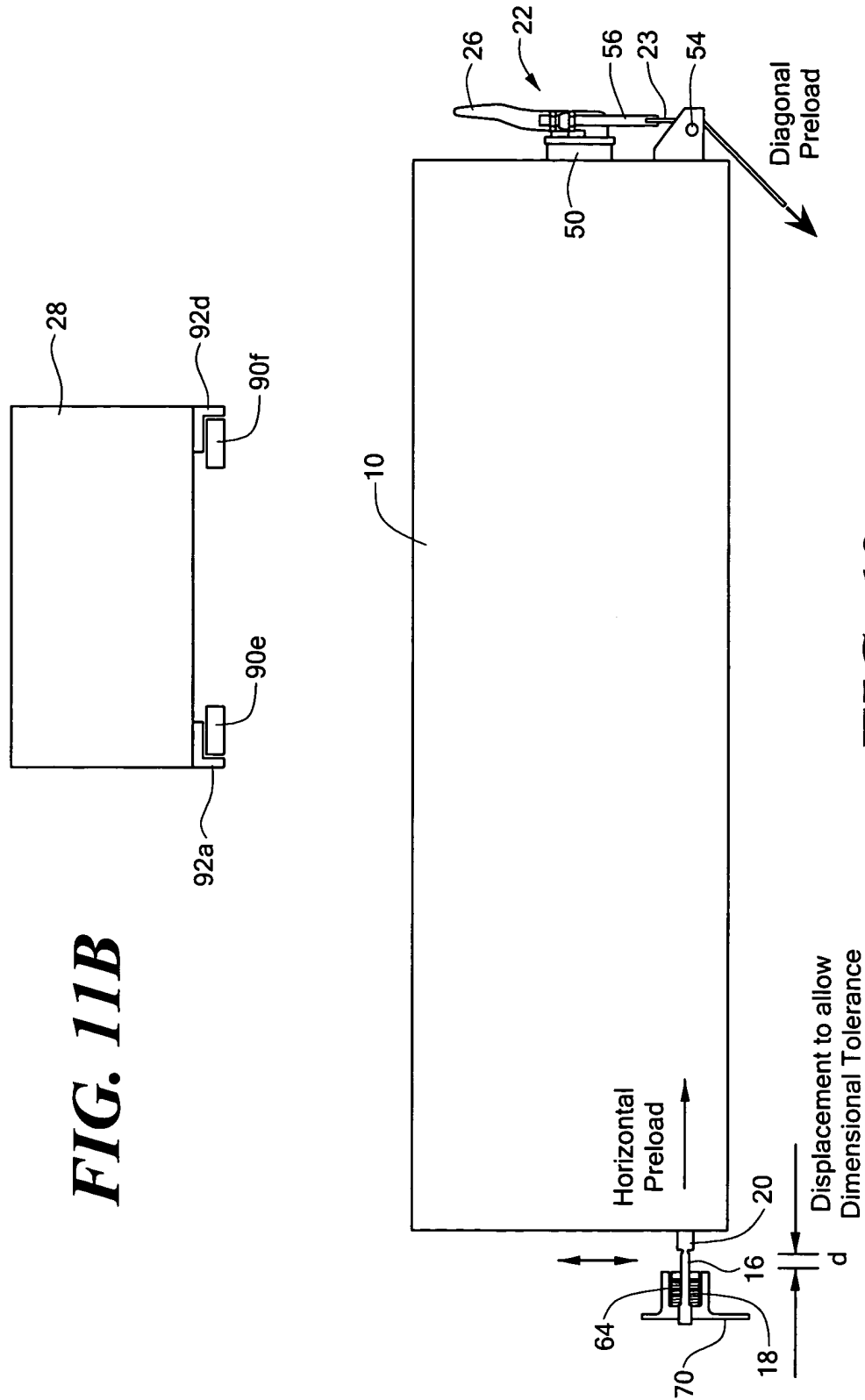
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**FIG. 11A**



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**FIG. 12**





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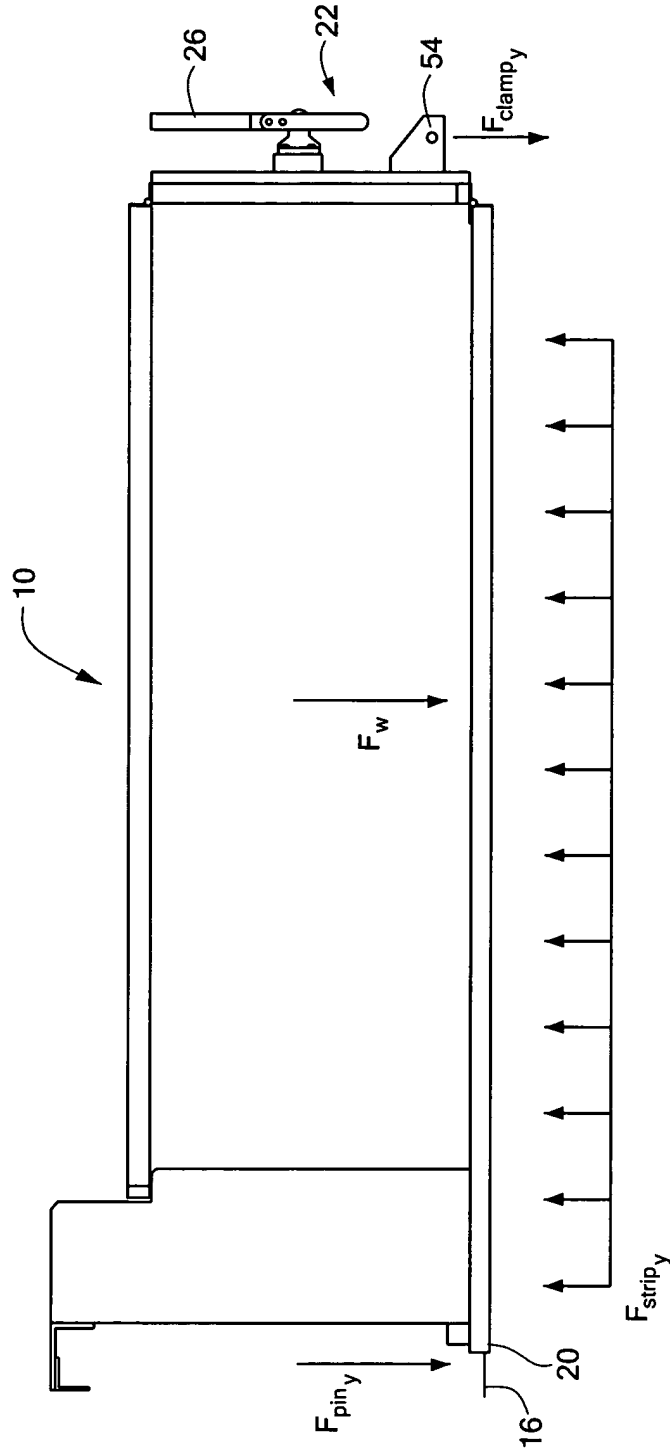


FIG. 13

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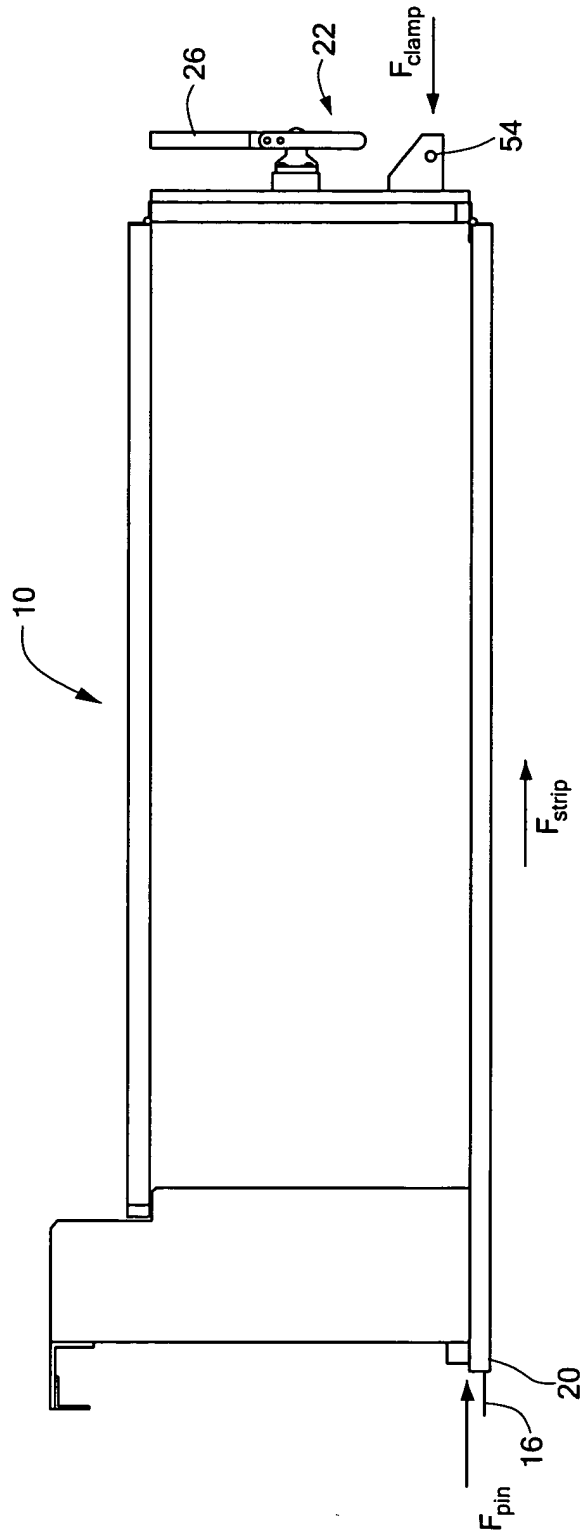
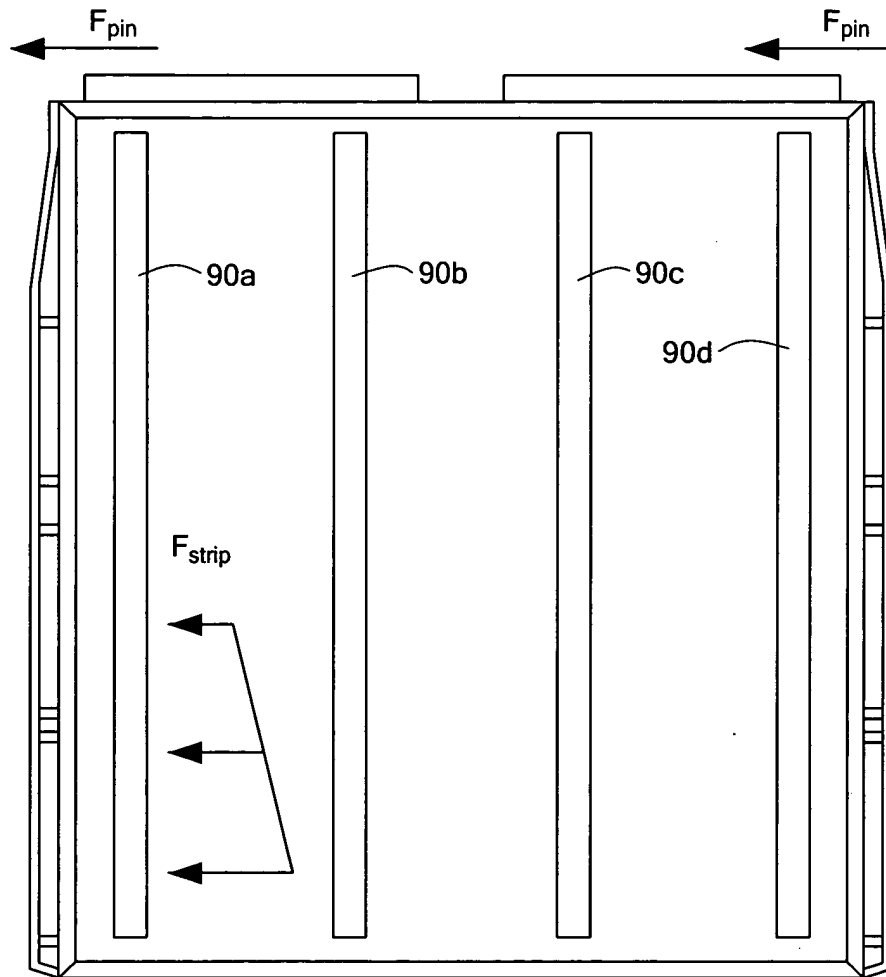


FIG. 14





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**FIG 15**